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## Distributed drift chamber design for rare particle detection in relativistic heavy ion collisions

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### Abstract

This report describes a multi plane drift chamber that was designed and constructed to function as a topological detector for the BNL AGS E896 rare particle experiment. The chamber was optimized for good spatial resolution, two track separation, and a high uniform efficiency while operating in a 1.6 T magnetic field and subjected to long term exposure from a 11.6 GeV/nucleon beam of  $10^6$  Au ions per second. © 2001 Elsevier Science B.V. All rights reserved.

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## 1. Introduction

In 1977, Jaffe predicted the existence of the  $H_0$ , a six-quark (uuddss) state bound with respect to strong decay [1]. Subsequent work by Donoghue et al. placed a weak decay lifetime for the  $H_0$  in the neighborhood of  $2\text{--}6 \times 10^{-9}$  s [2]. The possibility of this long lifetime, coupled with the copious production of Lambda hyperons (uds) observed in heavy ion collisions [3], led Baltz et al. to predict a large production of  $\Lambda\Lambda$  states in relativistic heavy ion collisions [4]. Assuming that the  $H_0$  has a substantial overlap with the  $\Lambda\Lambda$  state, heavy ion collisions should create a favorable environment for observing this uncharged exotic state.

The E896 experiment [5] was proposed to search for  $H_0$  production in relativistic Au + Au collisions at the Brookhaven National Laboratory (BNL) AGS. The experiment was designed to be sensitive to weak decay channels of neutral particles, and specifically optimized to detect the  $H_0 \rightarrow \Sigma^- + p$

decay channel. The main components of the experimental setup were two topological tracking detectors, shown in Fig. 1. One, a 15 plane silicon drift detector array, has been reported in a previous paper [6]. The other is a distributed drift chamber (DDC), located in a 1.6 T analyzing magnet with a 6.2 T sweeping magnet and collimator placed just upstream to minimize charged particles reaching the DDC. In the present paper, we discuss the design and implementation of the DDC.

## 2. Design

### 2.1. Designing the tracking detector

The primary constraints placed on the tracking detector in the E896 experiment were that it unambiguously identify the topological signature of particle decays, provide enough track information to reconstruct the rigidity of each charged daughter produced, and operate at high rates in a high flux environment. Given these restrictions, a DDC was the optimal detector for this experiment. A Multiwire Proportional Chamber would lack the spatial resolution (approximately an order of magnitude less than a drift chamber) necessary to reconstruct the invariant mass of the  $\Sigma^- + p$  channel and thereby distinguish it from the  $K^- + p$  background produced in  $n + n$  interactions. A Time Projection Chamber approach was not chosen due to insufficient double track resolution and because typical recovery rates are much slower than that of a drift chamber. A Drift Tube configuration was rejected because its mass is an order of magnitude larger than a DDC, as well as the fact that its assembly would be significantly more difficult.

For the physical size of the tracking detector, most of the outer dimensions were constrained by the bore of the 48D48 analyzing magnet. The 48D48 was chosen because it provides the largest fiducial volume of any of the standard BNL magnets with a strong enough magnetic field to allow identification of the daughter particles. The tracking detector (including electronics, cabling, etc.) is thereby constrained to be not more than

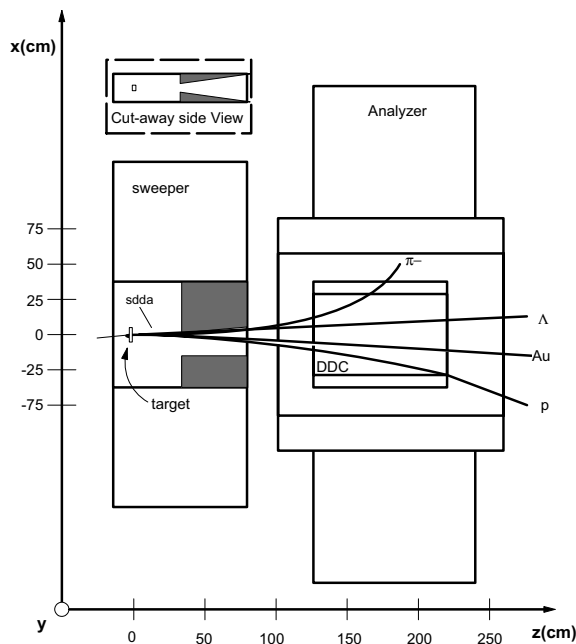


Fig. 1. Overview of the DDC system consisting of the target, sweeping magnet, collimator (black), DDC and analyzing magnet. The Z-axis is rotated  $-3.2^\circ$  from the incoming beam to center the produced neutral particles ( $\Lambda$ ) in the active part of the DDC.

45 cm in height, 120 cm in width, and 120 cm in depth. The inner or “working” area of the tracking detector was determined by a combination of the hardware constraints imposed by the sweeping magnet [7] and the simulations performed using GEANT [8]. The inner height of 20 cm is a compromise between maximizing the available tracking volume and allocating finite space for structural integrity and the necessary on-board electronics.

To reduce the number of neutral and charged particles interacting with the DDC structure, a 50 cm long lead–tungsten collimator was designed and placed 40 cm downstream of the target. A vertical opening angle of  $2.7^\circ$  was determined by GEANT simulations to be optimum for the system, effectively cutting the vertical acceptance of the DDC, 132 cm downstream of the target, in half. The maximum inner width of the tracking detector was determined by the background Monte Carlo. The results indicated that the central area of the chamber should be instrumented to detect the  $H_0$  decays, while the area containing the beam and lower rigidity positively charged beam fragments must remain sparse to reduce secondary interactions. Additionally, the low rigidity area on the negative bend side should also remain empty to reduce the background of  $\pi^-$  particles produced in the Au+Au collisions. Accordingly, the collimator was completely open in the  $X$  direction to beam right. To beam left the opening angle is drawn from the target pointing to the last beam left active wire in the most upstream part of the DDC. The chamber and magnets were oriented  $-3.2^\circ$  from the  $0^\circ$  beamline to maximize the acceptance around the mid-line for neutral particles produced in the target and to resolve charged daughter particles produced by their decays.

In the active area of the DDC, a minimum of 2 mm cell radius was required to produce enough primary electrons liberated by the passage of a minimum ionizing particle to be detectable. Simulations determined that this was sufficient granularity transverse to the direction of the magnetic field to resolve the two particles in the  $\Sigma^- + p$  channel. The required granularity along the beam direction ( $Z$ ) was determined to be  $\sim 0.5$  cm. This is a compromise among the need

for multiple measurements along the  $\Sigma^-$  track, the need to maximize the depth of the detector to increase the number of  $H_0$  decays observed, and the spatial constraints of on-board electronics used to outfit the instrument.

## 2.2. Cell configuration

The internal cell configuration was optimized by performing extensive simulations using GARFIELD [9]. The configurations which achieved the best spatial resolution were the ones in which the ratio of the cell width to depth was maximized. Since the cell radius is set to 2 mm, based on two-track separation and mechanical considerations the only option in maximizing the width to depth ratio was to minimize the cell depth. The cell half-depth was set at 3 mm, which is the minimum thickness having sufficient strength to support and maintain tension for the combination of anode and field shaping wires in the sense planes ( $\sim 5$  kg). GARFIELD simulations were run producing plots of lines of equipotential, in the presence of no magnetic field (Fig. 2a), drift lines in the presence of a 1.6 T field (Fig. 2b), and drift distance versus time. The  $4\text{ mm} \times 6\text{ mm}$  cell showed a “bleed” over of drift electrons to neighboring wires for only about 20% of the outer most tracks. An in-depth comparison of these results to actual data will be discussed in the following section. The 2 mm cell radius restriction was relaxed for the downstream half of the chamber where a larger cell size ( $8\text{ mm} \times 8\text{ mm}$ ) was used in this area where expanded coverage was more critical than double track resolution.<sup>1</sup>

Three different sense wire orientations,  $0^\circ(X)$ ,  $+15^\circ(T)$ , and  $-15^\circ(U)$  were chosen to obtain the required stereoscopic projection to allow momentum reconstruction. The  $T$  and  $U$  orientations were determined using tracking reconstruction of Monte Carlo data to maximize the  $P_y$  resolution while minimizing the confusion caused when multiple particles impact the same wire. Similarly, track reconstruction with

<sup>1</sup> This decision is based on an assumed  $H_0$  lifetime of between 4 and 100 cm  $c\tau$  for which the majority of the  $H_0$  decays in the DDC occur in the upstream half of the chamber

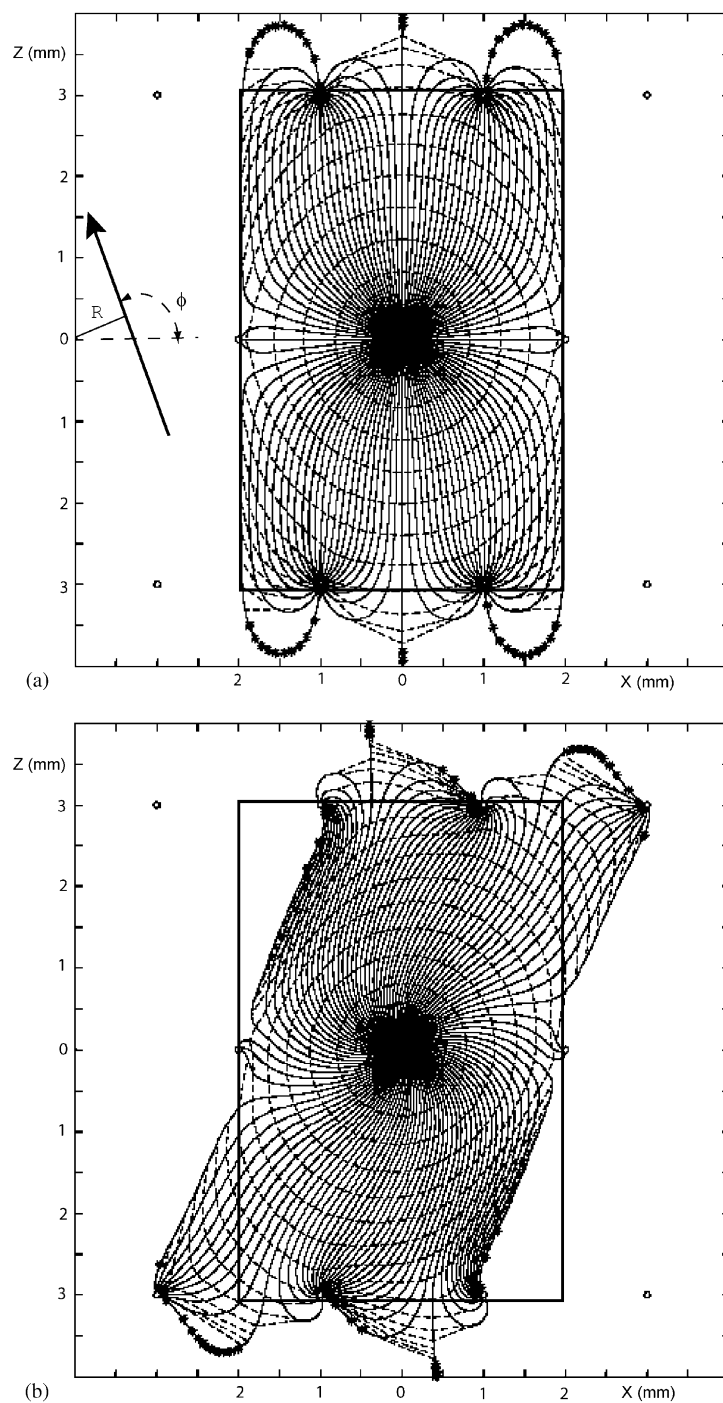


Fig. 2. (a) Garfield simulated trajectories of drifting electrons and the lines of equipotential for a single DDC cell with no magnetic field present. Note how none of the drift lines extend outside of the designated cell boundaries. (b) Garfield simulated trajectories of drifting electrons and the lines of equipotential for a single DDC cell in a 1.6 T vertical  $B_y$  field. Note how many of the drift lines extend outside the designated cell boundaries and into the adjoining cells.

momentum analysis was used to optimize the final plane sequencing,  $XX'UU'XX'XX'TT'XX'$  (primes designate planes with cells shifted by half a cell's width with respect to an unprimed plane).

### 2.3. Internal construction

Once the overall size, shape, and type of tracking detector had been fixed, the construction materials and the internal configuration were determined. The field shaping cathode planes were constructed with conducting foils rather than wires due to the field problems that arise in transitioning between sense wires with different orientations. The use of foils places stringent requirements on the flatness and spacing uniformity of the NEMA G10 cathode mounting frames. We were able to hold individual frame tolerances to  $< \pm 15 \mu\text{m}$  over a 1 m distance. G10 was chosen for both its structural strength and electronic insulating properties. Further, cryogenic grade G10 was chosen to avoid any problems with boron contaminants which are known to bind with free electrons and cause a loss of signal. A carbon impregnated foil used in electromagnetic pulse (EMP) technology was chosen over the more common aluminized or silver deposited mylar due to its bulk conductive properties. These allowed a single foil to be shared between two sense planes to provide the shaping potential. The bulk conductive properties also reduced the chance of charge build up and subsequent discharge to the sense wires. To avoid electric field problems being induced by foil edges (e.g. break down, polymerization of wires, etc.), the foils were stretched across the entire width and breadth of the G10 frames. This meant extending them into both the  $\pi^-$  and beam regions.

The potential for beam-foil interactions was reduced by removing a 3 cm diameter area from each foil centered along the expected beam trajectory. To avoid electric field anomalies at the edges of the active region, the sense wires were bounded with a final cell containing a larger diameter terminating wire tied directly to ground. To obtain the amplification required by the front end electronics (FEE) and to avoid avalanche problems,  $20 \mu\text{m}$  diameter gold-plated tungsten wire was chosen for the sense wires. The tensile

strength of tungsten allows for the smallest diameter wire, hence greatest electric fields with lower voltages. The gold plating provides a smoothness which makes for a more uniform field over the length of the wire. It also allows the wires to be soldered. The terminating anode wire on either end of the sense planes is  $75 \mu\text{m}$  beryllium-copper with a 5% gold strike, the same as the cathode wires used for shaping the field around each anode (sense) wire.

The use of foils also required special attention to eliminate any gas flow restrictions which might create pockets in the chamber which would lead to anomalous drift characteristics. One centimeter diameter holes were placed in alternate corners of each foil and 8 h purges were required after any opening of the chamber. This design was sufficient to guarantee uniformity in the drift properties. The stability of the drift properties of the gas was monitored during the experiment by connecting the DDC gas output to a single wire TPC containing an internal  $^{106}\text{Ru}$  source, the so-called canary.

### 2.4. Constraints on drift gas

Although the portion of the chamber where beam and projectile fragments pass is not active, it still contains chamber gas. Thus, it is preferable to use a helium-based gas to reduce the number of delta rays and secondary interactions produced in the gas by the primary beam and projectile fragments. A 50%:50% mix of helium (He) and ethane ( $\text{C}_2\text{H}_6$ ) bubbled through methyl alcohol was chosen. The introduction of 1–5% methyl alcohol is known to reduce polymerization of wires, or “aging”, in drift chambers [10]. An additional reason for using a helium-based gas is that the drift velocity is less sensitive to the magnetic field than in an argon-based gas [11]. The effect of the magnetic field on pulse height is also reduced [12]. The gas mixture flowed continuously through the DDC at a pressure slightly above atmospheric.

### 2.5. Mechanical construction

All wires are epoxied to the G10 frames to maintain their tension, then soldered to internal

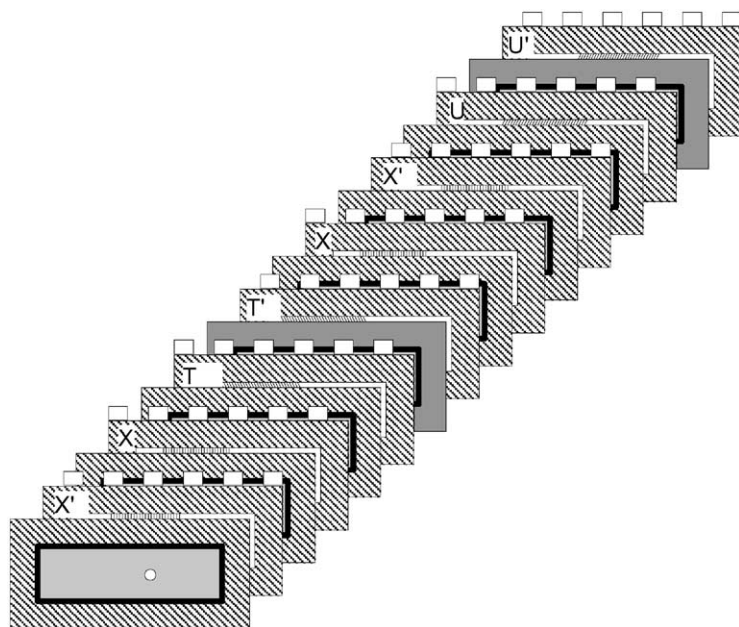


Fig. 3. DDC modules are constructed by alternating 12 of the laminated sense planes in the proper order ( $XX'TT'XX'XX'UU'XX'$ ) with 12 HV foil planes.

artwork etched onto the frames. Twelve sense ( $XX'UU'XX'XX'TT'XX'$ ) and 12 foil planes, each outfitted with a 30 durometer butylene O-ring, are bound together with 316-SS (Stainless Steel) posts and flathead binder screws to form a single module, shown in Fig. 3. The planes were indexed to each other using three anodized pins for an interplane wire accuracy of  $\sim 10\ \mu\text{m}$ . These pins also facilitated indexing neighboring modules to within an accuracy of  $\sim 40\ \mu\text{m}$ . The survey of the entire DDC with respect to other elements in the experiment was completed with an accuracy of  $\sim 70\ \mu\text{m}$ . The modules are 7.2 and 9.6 cm deep for the 6 mm deep cells and 8 mm deep cells, respectively. The 6 mm modules had 64 sense wires per plane and the 8 mm modules had 46. The foil planes between  $UU'$  and  $TT'$  sense planes were constructed by replacing the G10 frame with a prestressed 316-SS frame laminated with kapton artwork. The two stainless frames created a bridge structure for each module to maintain wire tension and module alignment.

Each module is equipped with a pillow block assembly on each of its lower corners to allow

mounting to a rail system. The rigidity and alignment of the complete DDC is accomplished by binding the 12 modules<sup>2</sup> between a 1.27 cm aluminum frame and an aluminum “strongback”, composed of a similar 1.27 cm aluminum frame and 7.5 cm box beam. Twenty-four 1 m long threaded rods brought the assembly together to form a gas-tight volume. Both the frames and strongback were ground flat to  $15\ \mu\text{m}$  and outfitted with two gold-plated mylar windows each. Gas was exhausted through the region between the windows on either frame thus functioning as a buffer to prevent moisture from entering the active region of the chamber and to avoid changing the He to  $\text{C}_2\text{H}_6$  ratio in the active region near the windows. The assembled DDC was mounted on the rail system to enable it to slide into the 48D48 magnet when outfitted with cable trays, nitrogen cooling ducts, and cabled with 34 pin twist-n-flat cables as shown in Fig. 4.

<sup>2</sup>For a total of 144 planes (i.e. six 6 mm modules and six 8 mm modules).



Fig. 4. The completed drift chamber with cables being inserted in the 48D48 analyzing magnet.

### 3. Electronics

#### 3.1. HV distribution

A 1 mm connector was embedded into the edge of each frame and soldered to the internal artwork to allow for a high voltage (HV) connection. Two channels of a LeCroy 1440N HV supply were assigned to each module. Each of these 1440N channels supplied a HV Bus card, containing 12 mating connectors, which distributed HV to an entire module's foil or sense planes. The HV bus card routed the 1440N HV to each connector via a field effect transistor (FET). A power distribution panel for the FETs was constructed to allow disabling HV to individual planes of the DDC as required. A Labview interface was developed to monitor and control the HV system.

#### 3.2. Front end cards

Constraints placed on the electronics for this detector were as stringent as the mechanical requirements. Specifically, the FEE required short shaping time for good double pulse resolution, low power because of the large number of channels

and restricted space, high channel density, and low operational threshold. Due to these restrictions, the experiment chose to develop a custom FEE board that utilized the ASD8 chip already in use by PHENIX at RHIC [13]. The ASD8 is an 8-channel amplifier, shaper, and discriminator integrated circuit, constructed in an npn bipolar process for low noise, high speed, and high gain power efficiency. It provides a low operational threshold ( $\sim 1$  fC), suitable shaping time ( $\sim 5$  ns), and good double pulse resolution ( $\sim 20$  ns), all with low power consumption ( $\sim 15$  mW/chnl). Even with this low power consumption it was necessary to flow cold nitrogen gas over the FEE cards to keep their temperature below  $50^\circ\text{C}$ .

The FEE card was designed to service 16 sense wires. As such the card contained two ASD8s, each consisting of eight identical ASD channels with differential inputs and outputs. Since the low threshold readout is susceptible to interference pickup, the FEE cards were mounted directly on the chamber. One side of the differential input was connected via a copper trace masked on the G10 frame to a sense wire while its differential was connected to a companion trace which was left unterminated. The FEE cards were mounted on

the top of the chamber, each bolted with a solid ground connection to a silver plated brass ground plate which covered the entire top surface of the G10 frames. The signal connectors, edge mounted on the G10 frames, protruded through slots in this ground plate to connect to the FEE cards.

### 3.3. Readout

Another desirable feature of the ASD8 chip was that its differential output was compatible with the ECL input required by the LeCroy 1879 fastbus TDCs used in the experiment. The 96-channel pipeline TDC was chosen for its high density and speed. The 2 ns resolution set construction tolerances for the DDC at  $\pm 70 \mu\text{m}$ . The size of the 1879 readout buffer was reduced to increase data collection speed and still maintain multihit capability in the useful time range. The LRS 1810 Clock and Trigger (CAT) module was used to provide the calibration and common stop trigger signals to the 1879s. Event readout of the four fastbus crates into an LRS 1190 VME memory module was via LRS 1821 segment managers.

## 4. Calibration

Approximately  $1.2 \times 10^8$  events were recorded from 11.6 A GeV/c Au + Au collisions using the DDC during a 4-week period in April of 1998. A second run, which produced  $6 \times 10^6$  events using a beam of 12 GeV/c protons on a Be target, was staged in September of 1998. Data from both these runs were used to calibrate and characterize the DDC as discussed in the following sections [14].

## 5. Time calibration

Time calibration of the system was accomplished by pulsing either the FEE cards or the HV foils and issuing a subsequent stop pulse to the TDCs via the CAT module after a set period of time. An Ortec 462 Time Calibrator with an accuracy of 50 ps was utilized for this procedure. The calibration pulse was input to the HV distribution cards discussed above which served

to distribute the time calibration pulses to the HV foils and isolate the Ortec 462 unit from the LRS 1440 HV supply powering the foils.

The TDC offsets were determined on a per run basis for each TDC channel. To determine the offset for a particular channel, the TDC values were histogrammed for a sample of events and the resulting spectrum was subject to an edge finding algorithm. The edge finding algorithm involved fitting a half-Gaussian to the leading edges of the TDC spectra and then calculating the TDC value that corresponded to half the maximum value of the Gaussian.

In order to flag sections of the DDC that suffered from very low efficiency or noisy electronics, software was developed to generate a “kill file” on a per run basis. For each wire in the DDC the hit occupancy, mean TDC value and rms TDC value were determined for each run. Wires for which these summary statistics did not fall within a particular range were written to a kill file. The kill file was subsequently read in by the tracking software and the wires therein were not used to constrain tracks. The use of the kill file improved the momentum resolution by eliminating noisy wires and increased the track finding efficiency by decreasing the number of instances that the finding software incorrectly located a track’s endpoint within a dead section.

### 5.1. Drift curve calibration

The determination of the correlation between the local parameters of a track crossing a drift cell and the measured drift time is an essential calibration for drift chamber detectors. The presence of a magnetic field introduces a velocity-dependent term from the Lorentz force equation and thus complicates the drift behavior of the ionization electrons. The elliptical and circular lines shown in Fig. 2 are lines of constant drift time or isochrones. In the absence of magnetic field effects, these lines are concentric circles centered at the location of the sense wire. The magnetic field distorts the geometry of the drift cell and renders the lines of constant drift time furthest from the sense wire elliptical in shape. This effectively introduces an angular



dependence in the correlation between the distance of closest approach (between a charged track and the sense wire) and the measured drift time. In the case in which there is no magnetic field, the locus of points corresponding to a fixed distance of closest approach corresponds exactly to a circular isochrone, hence there is no angular dependence. In the presence of a magnetic field, the relevant isochrone is dependent on both the distance of closest approach and the angle at which the charged track crosses the drift cell.

### 5.2. Garfield

Garfield [9] is a computer program for the simulation of two- and three-dimensional drift chambers. The program exactly solves electrostatics in two dimensions using conformal mapping techniques. It also models diffusion, particle drift, avalanches, and signal generation. The program can be used to generate field maps and drift time to drift distance correlations. The parameters chosen to describe the correlation between a track crossing and measured drift time were the distance of closest approach and the angle the bend plane track tangent made with the cave  $X$ -axis. Garfield was used in an initial simulation of the characteristics of the DDC drift cells. A goal of this simulation was the determination of the relative importance of the distortions due to the presence of a large magnetic field. Fig. 5 shows the Garfield generated correlation between  $t$  (the measured drift time) and  $R$  (the distance of closest approach between the track segment and the sense wire) for three different values of the angle  $\phi$ . The Garfield simulation indicated that the deviations between drift curves of differing angle were  $> 2$  ns (the resolution of the 1879 TDCs) over 60% of the drift cell.

### 5.3. Measured drift correlations

The actual drift correlations were determined using a sample of rigid protons from the September 1998 proton run. Tracks were initially fit using the Garfield-based approximation to the true drift correlations. The best fit track parameters were then extrapolated to each active detector cell and

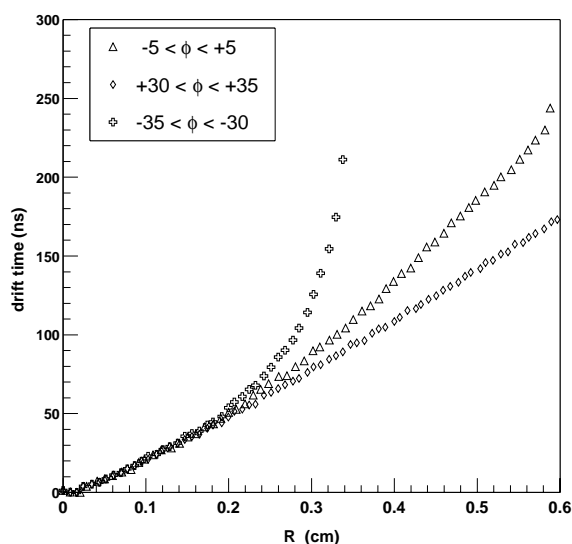


Fig. 5. Garfield generated correlation between drift time  $t$  and distance of closest approach  $R$ , for three values of  $\phi$ .

the distance of closest approach was plotted versus the measured TDC values in bins of the angular variable  $\phi$ . The resulting drift correlations were parameterized and then used as input for subsequent iterations. The process was repeated until variations in the parameterization were of the same order as the detector resolution. Fig. 6 shows a family of drift correlations as determined by this method, taken from the final iteration for the 8 mm drift cells. As anticipated, deviations due to angular effects are visible at a level comparable to the resolution of the detector for  $R > 0.3$  cm.

### 5.4. Parameterization of drift correlations

The DDC drift correlations were parameterized using  $C^1$  continuous splines. The requirement of continuous derivatives across break points was necessary because, as will be described later, the measurement error associated with a given value of  $R$  was taken to be proportional to the slope of the drift curve. Therefore, discontinuities in the derivatives would translate into discontinuities in the  $\chi^2$  minimization algorithm. The parameterization

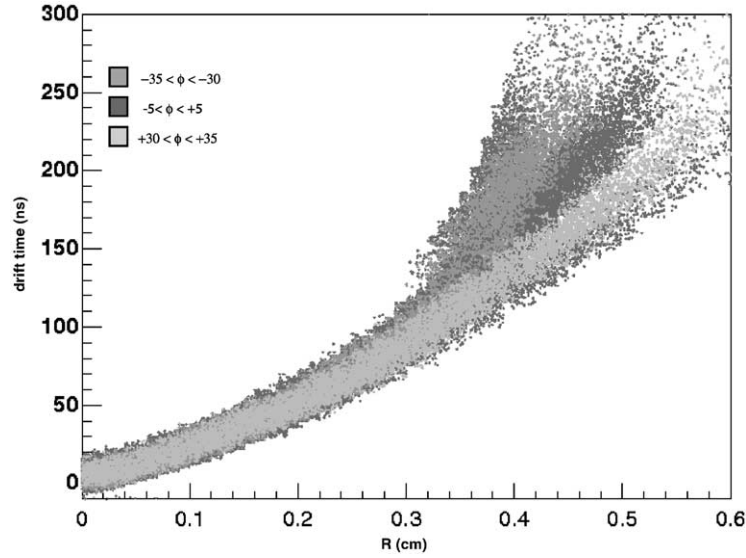


Fig. 6. Measured drift correlations. Data were binned in  $\phi$ , and the distance of closest approach (cm) versus measured drift time (ns) is plotted.

Table 1  
Drift curve parameters

Cell(mm)	$\phi$ (rad)	$p_1$ (ns)	$p_2$ (ns/cm)	$p_3$ (ns/cm <sup>2</sup> )	$p_4$ (ns/cm <sup>3</sup> )	$p_5$ (ns/cm)	$b_1$ (cm)	$b_2$ (cm)
4	0.0	1.82	107.21	568.14	3034.90	467.77	0.2	0.35
4	0.4	0.70	103.98	604.21	9207.20	10976.0	0.2	0.35
4	-0.4	0.35	170.67	927.06	-839.64	491.57	0.2	0.35
3	0.0	3.84	94.49	580.47	8009.4	3076.1	0.10	0.15
3	-0.4	2.08	139.77	397.80	-3118.9	678.27	0.1	0.15

used is shown in Eq. (1).

$$t_1(0 < R \leq b_1) = p_1 + p_2 R + p_3 R^2$$

$$t_2(b_1 < R \leq b_2) = t_1(b_1) + t'_1(R - b_1) + p_3(R - b_1)^2 + p_4(R - b_1)^3$$

$$t_3(R > b_2) = t_2(b_2) + t'_2(R - b_2) + p_5(R - b_2) \quad (1)$$

where  $t'_1$  and  $t'_2$  equal  $dt_1/dR$  and  $dt_2/dR$ , respectively. The values of the parameters were derived via a maximum likelihood fit to the data. The break points were adjusted manually. The data were divided into angular bins and the fit parameters determined for each bin. For  $\phi$  values inside the angular range of the fits, linear inter-

polation between the two nearest drift curves was used. For values outside this range the closest drift curve was used. Table 1 shows the fit parameters and break points for the various angular bins.

##### 5.5. Characterization of DDC errors

Despite the presence of the sweeper magnet, the charged track background in the DDC made  $\chi^2$  increment based outlier rejection necessary. This is accomplished by initially constraining the track with all the hits associated by the pattern recognition software. Then, if the  $\chi^2$  increment contributed by a given hit is more than a user defined threshold, the hit is rejected. Rejected hits are typically associated with charged tracks other than

the one being fit, or with noisy DDC electronics. The definition of the  $\chi^2$  increment is given as

$$\chi_{\text{inc}}^2 = [(t_m - t_p)/\sigma_t]^2 \quad (2)$$

where  $t_m$  and  $t_p$  are the measured and predicted drift time, respectively, and  $\sigma_t$  is the statistical error.

The non-linear correlation between drift time and distance of closest approach implies the measured error also varies as a function of the cell local track parameters. Fig. 7 shows the parameterized drift curves offset by  $\pm 3\sigma$  errors, and superimposed upon measured drift correlations. In Fig. 7a, a constant error is used, in Fig. 7b the error is parameterized as

$$\sigma_t = \sigma_{\text{TDC}} + (dt/dR)\sigma_{\text{POS}} \quad (3)$$

where  $\sigma_{\text{TDC}}$  and  $\sigma_{\text{POS}}$  are constants and  $dt/dR$  is the slope of the drift curve. It is clear that the constant error parameterization underestimates the error for large values of  $R$ , whereas the parameterization of Eq. (3) more accurately reflects the actual errors. Consequently, the latter was used in the track reconstruction.

### 5.6. Detector resolution

The values of the constants were determined by requiring the pull statistic given by

$$p = (t_m - t_p)/\sigma_t \quad (4)$$

be unbiased and of unit variance. Fig. 8 shows the distribution of the pull statistic for the 6 mm drift cell. The parameters used are shown in Table 2. The fact that the distribution of pull statistics is unbiased indicates that the parameterization of the drift curves is not systematically biased. The unit variance of the pull distribution is required for  $p^2$  to have a  $\chi^2$  distribution. As indicated in the table, the average position resolution for the cells was better than 160  $\mu\text{m}$ .

### 5.7. Efficiency calibration

The per plane efficiency was determined by reconstructing a sample of long straight tracks that left hits in the first and last modules of the DDC. The reconstructed track parameters were extra-

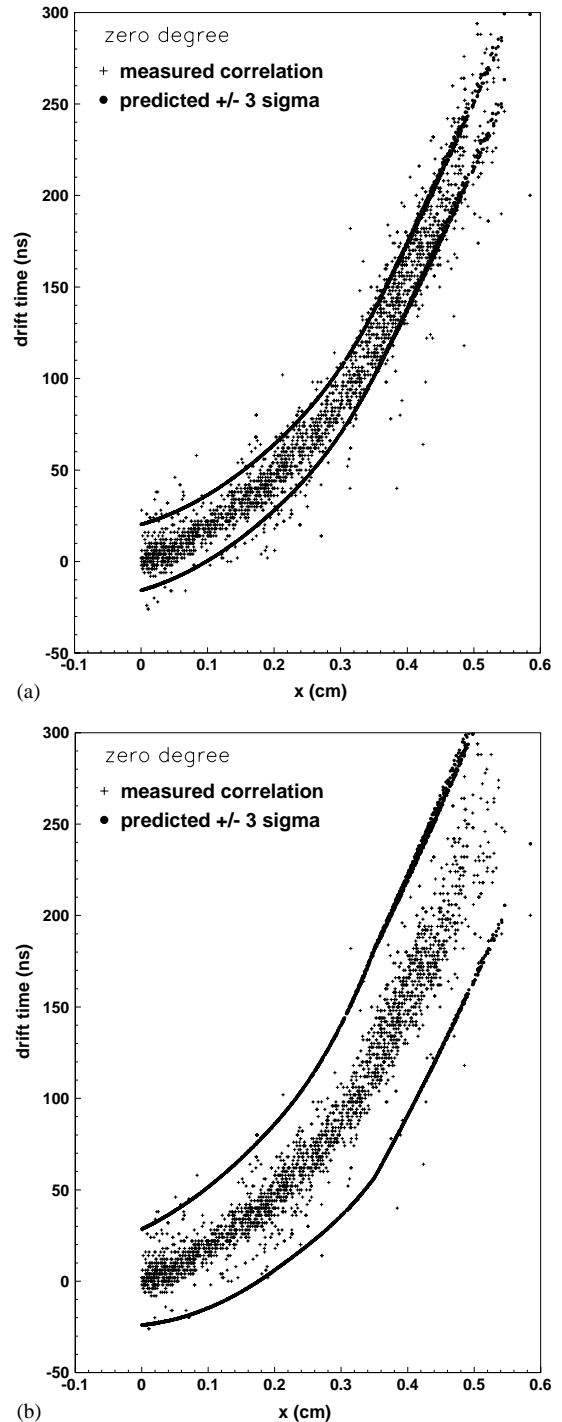


Fig. 7. (a) Parameterization of drift curve offset by  $\pm 3\sigma$  errors. The errors were parameterized by  $\sigma_t = \text{constant}$ . (b) Parameterization of drift curve offset by  $\pm 3\sigma$  errors. The errors were parameterized by  $\sigma_t = \sigma_{\text{TDC}} + (dt/dR)\sigma_{\text{POS}}$ .

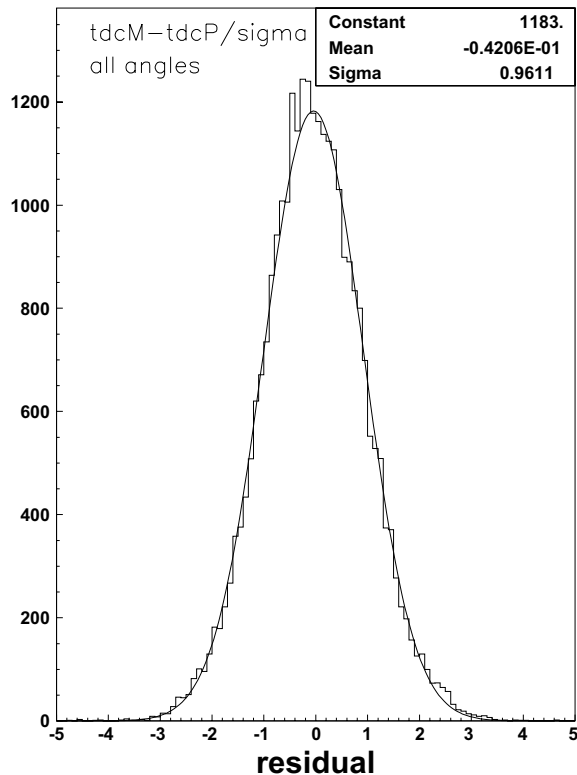


Fig. 8. Pull distribution for a 4 mm  $\times$  6 mm drift cell.

Table 2  
Drift chamber resolution

Cell type(mm)	$\sigma_{TDC}(\text{ns})$	$\sigma_{POS}(\mu\text{m})$
4	4.27	160
3	3.35	140

polated to each detector plane and the nearest two sense wires were checked for a hit. The efficiency was defined as the ratio of hits to plane crossings. Wires that were killed because of low efficiency or noisy electronics were not used in the calculation of the efficiency. In other words, if a track intersected a plane in a killed region neither the hits nor crossing counter was incremented. Fig. 9 shows the per plane efficiency averaged over a sample of runs from the late portion of the 1998

AuAu run. The following systematic effects were observed:

1. The modules of 6 mm deep cells were on average 7% less efficient than that of the modules with 8 mm deep cells. This is to be expected due to the shorter track length in the 6 mm cells and the correspondingly fewer primary drift electrons initially generated.
2. The planes that directly followed a stainless steel strong frame ( $T'$  and  $U'$ ) were systematically less efficient, because the higher capacitance on the signal lines in planes adjacent to these planes.
3. There was a systematic loss of efficiency observed in the first two modules of 6 mm deep cells and the last module of 8 mm deep cells.
4. The loss of efficiency observed in the last module of 8 mm deep cells was correlated with the beam flux. At beam rates above 50 K per AGS spill, the inefficiency in the rear of the chamber increased dramatically independent of target thickness.

## 6. Summary and conclusions

A distributed drift chamber was built and used in a rare particle search at the BNL AGS. The design of the chamber was optimized for resolving  $V$  topologies while operating in a strong magnetic field and a high flux environment. The chamber met these design specifications, providing high quality data in a 11.6 A GeV/c beam of  $10^8$  Au ions per second. An example of a  $\Lambda$  decay in the drift chamber is shown in Fig. 10. The He:C<sub>2</sub>H<sub>6</sub> gas used successfully minimized secondary interactions and multiple scattering in the chamber. Due to the presence of the strong magnetic field, the correlation between drift time and trajectory angle was found to play an important role in correlation of time to distance. The overall chamber performance was not affected by the non-uniformity in the magnetic field of the analyzing magnet. The wires were positioned with sufficient accuracy (10  $\mu\text{m}$ ) to achieve a single wire resolution of better than 160  $\mu\text{m}$  and plane efficiencies up to 97%. As designed and constructed, the DDC should be

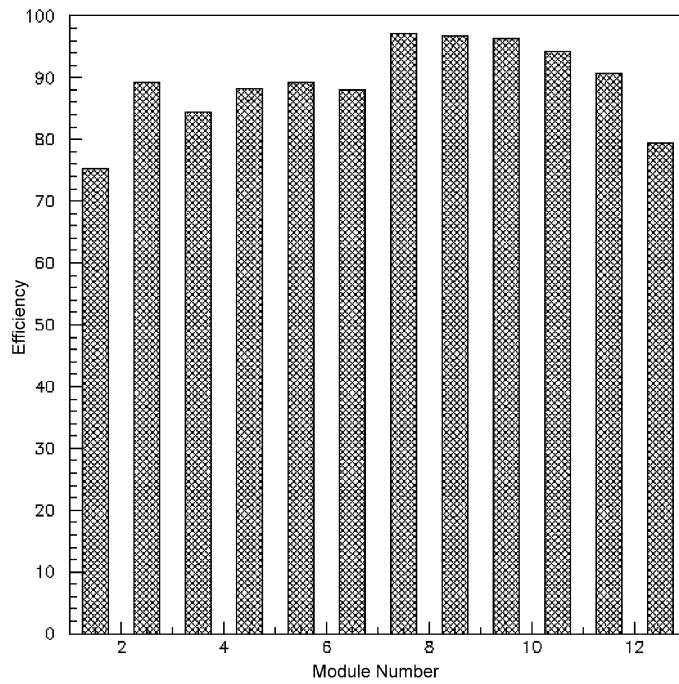


Fig. 9. Bars represent the efficiency per module for the 1998 Au run. Efficiencies were obtained by averaging the per plane efficiency of the 12 planes in each module.

Run2885, event63000152  
x wires.

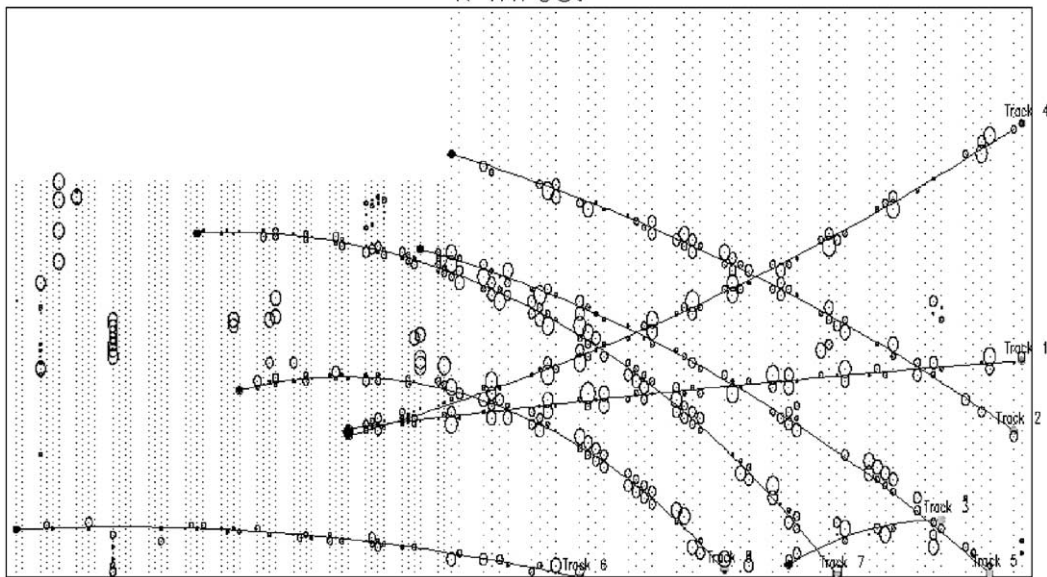


Fig. 10. A  $\Lambda$  decay to pion and proton as found in a typical event from the AuAu run. Note the clean neutral vertex and the low track background.

over 99% efficient in reconstructing the expected  $\Sigma^-$  tracks coming from an  $H_0 \rightarrow \Sigma^- + p$ .

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